

Figure 1

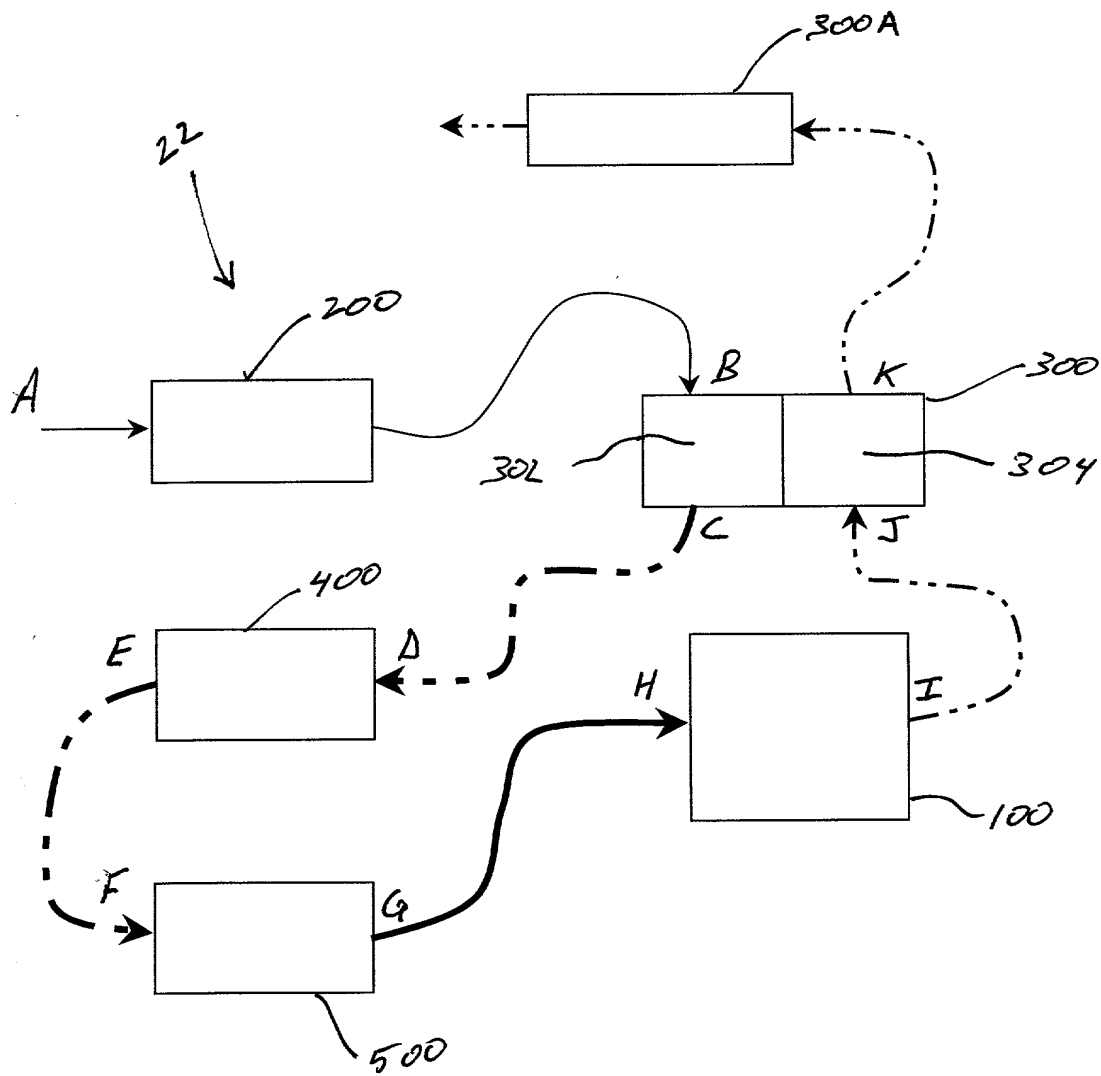


Figure 2

Figure 3 is a perspective view of a robotic arm assembly 22. The assembly includes a base 200 with a display screen 202 and a control panel 204. A robotic arm 100 is mounted on the base, featuring a joint 102 and a gripper 104. The gripper has two fingers 106 and 108. A cable 24 is connected to the base. A large rectangular component 500 is positioned to the right of the arm. Various other components are labeled with reference numerals.

Figure 3

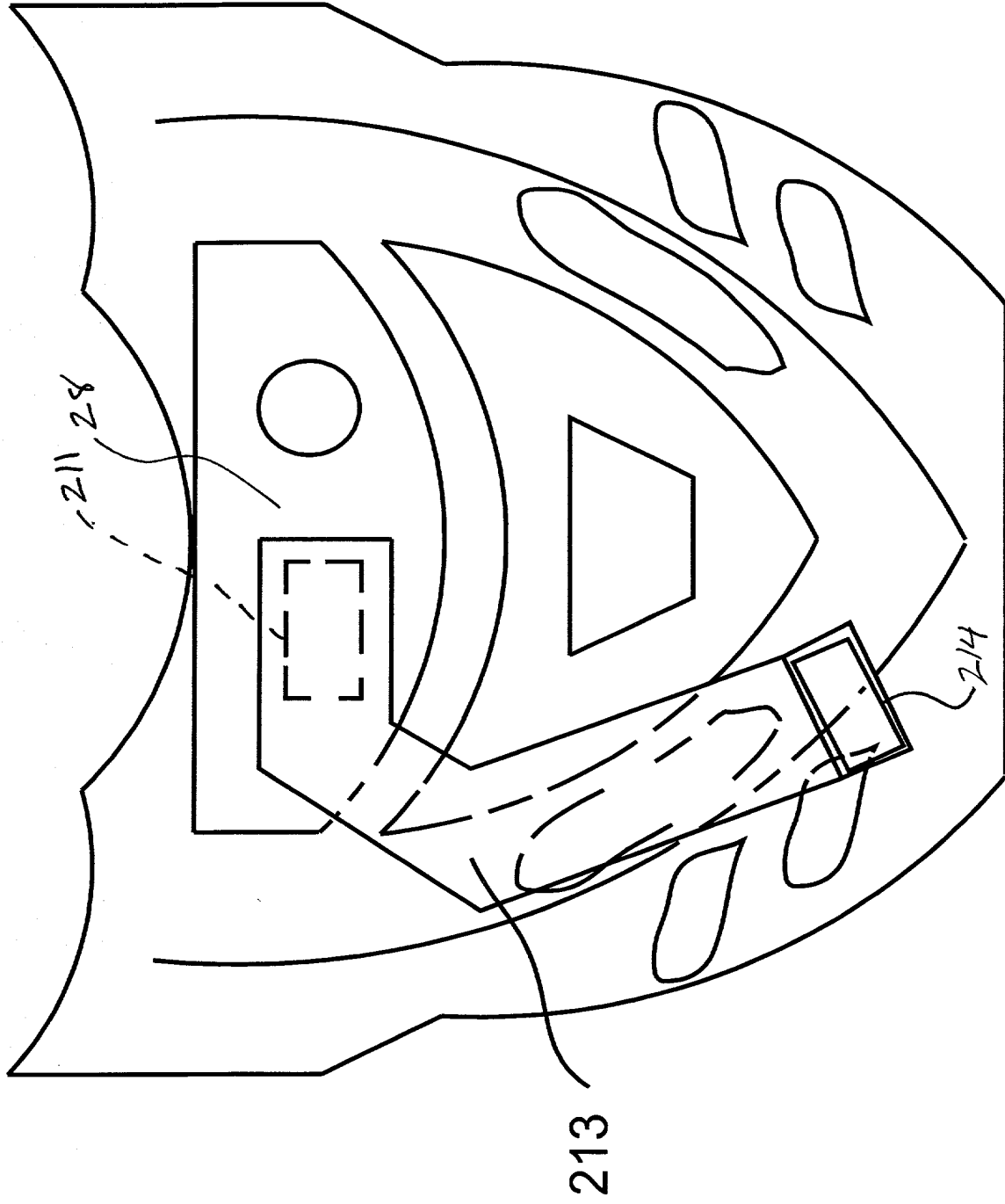


FIGURE 4

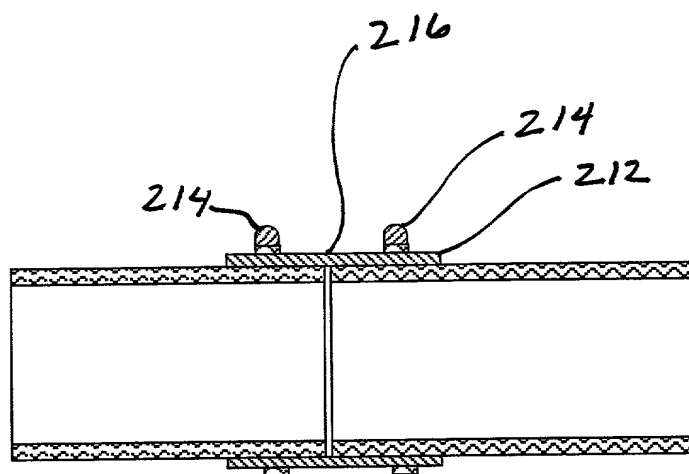


Figure 5

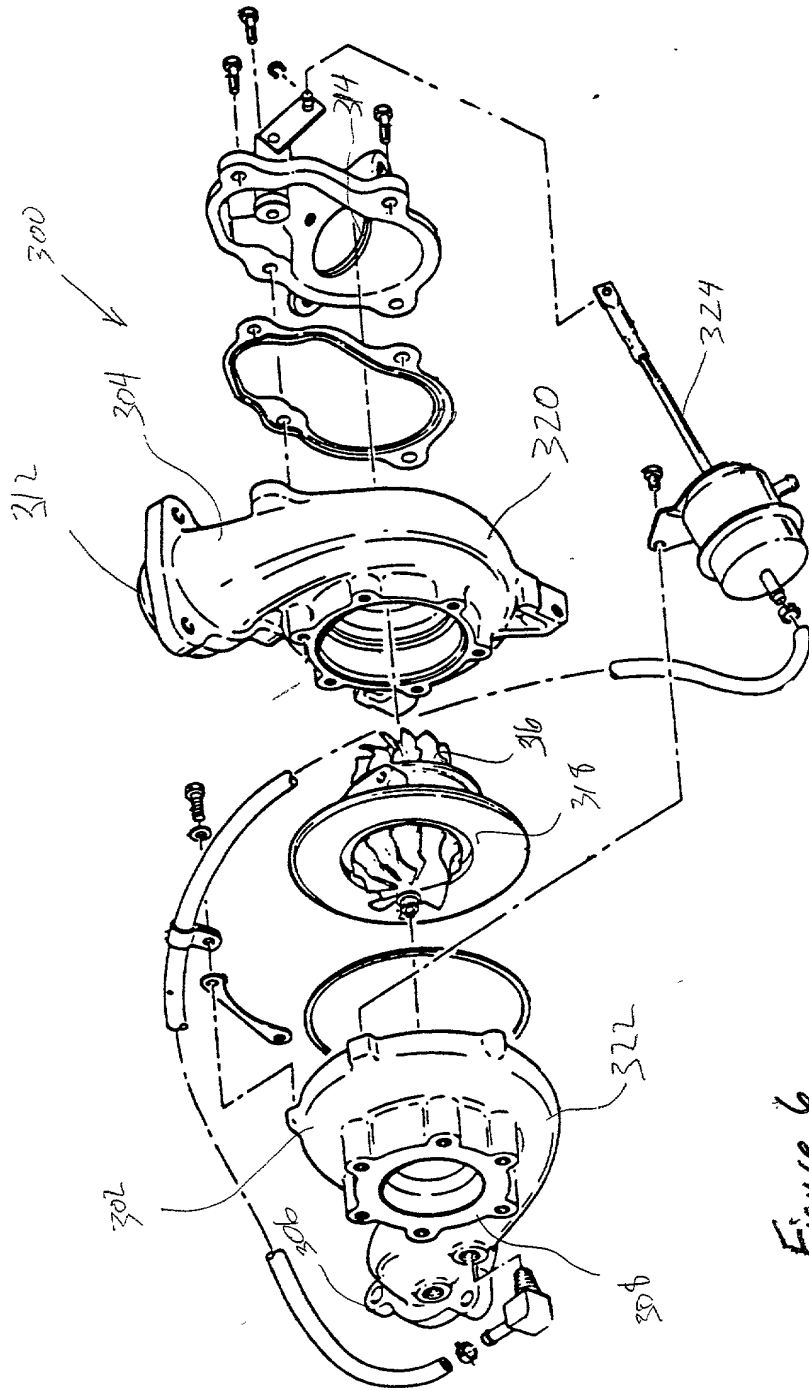


Figure 6

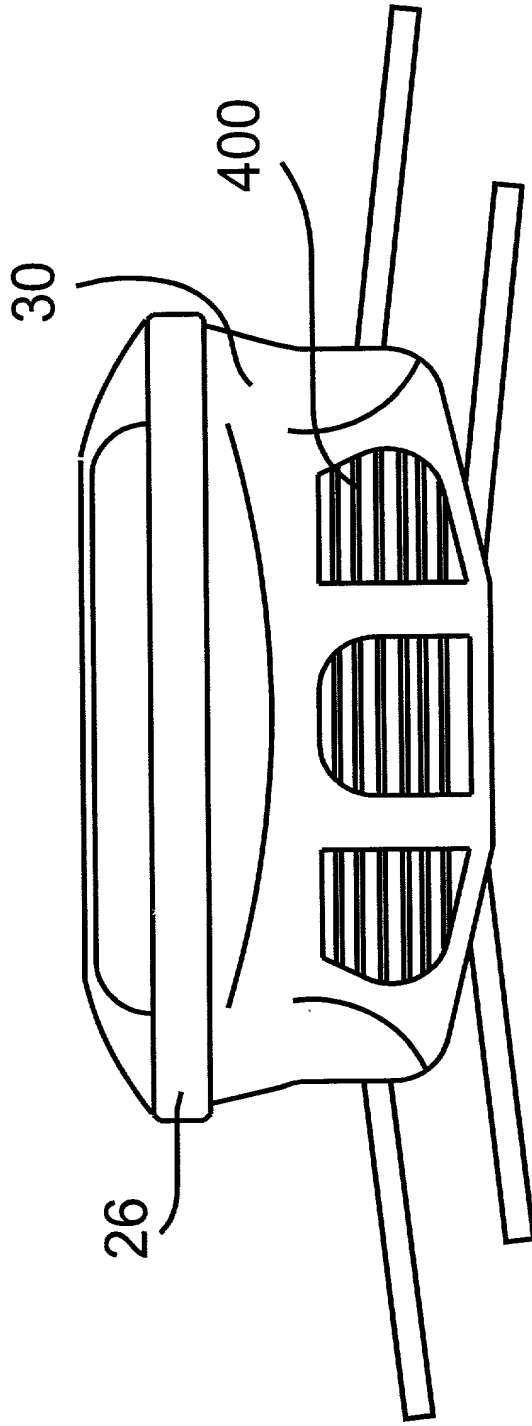


FIGURE 7

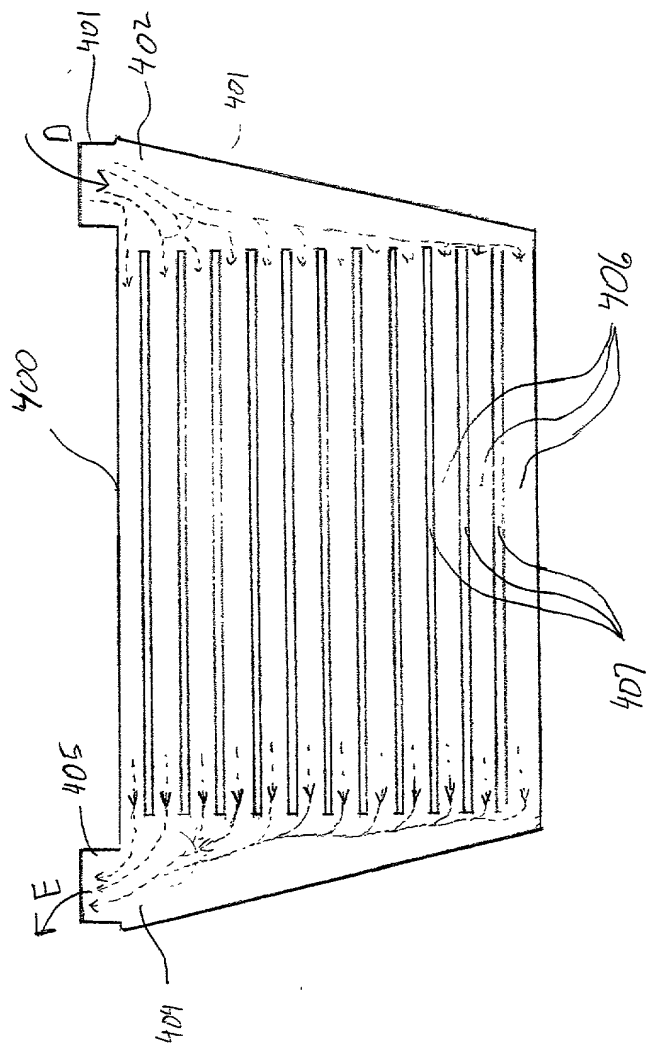


Figure 8



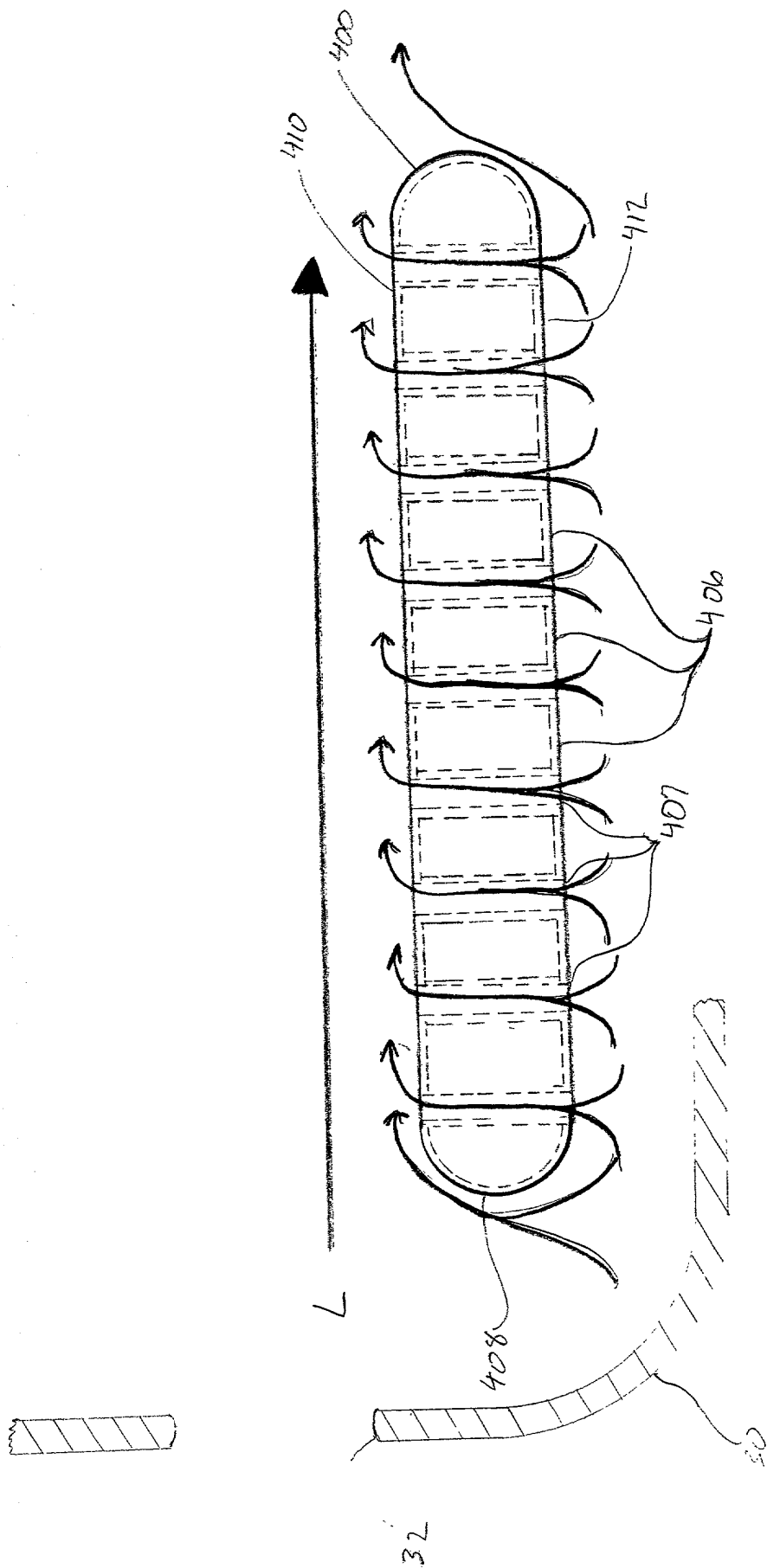


Figure 9

Patent 2004/006660

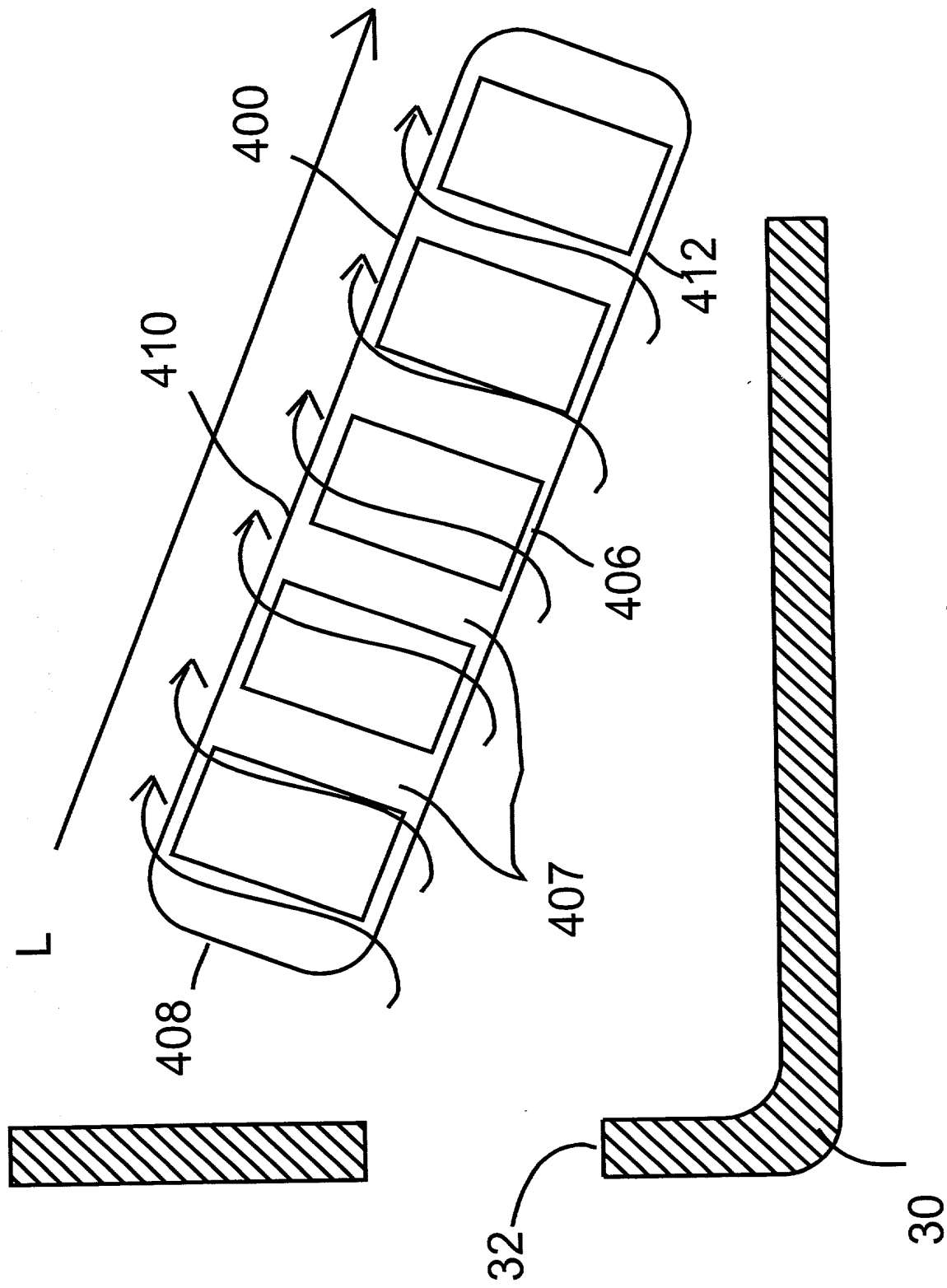


FIGURE 10

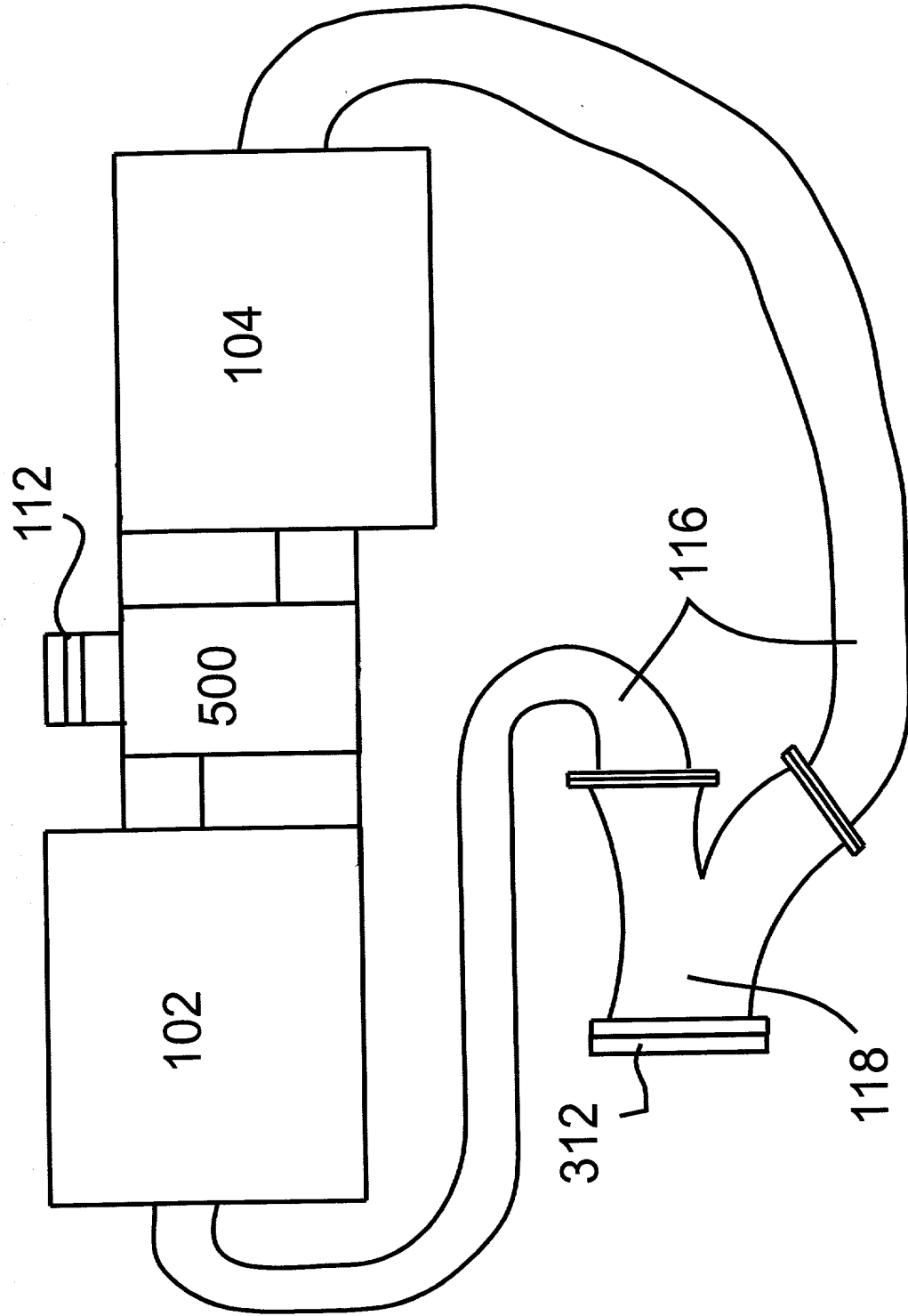


FIGURE 11

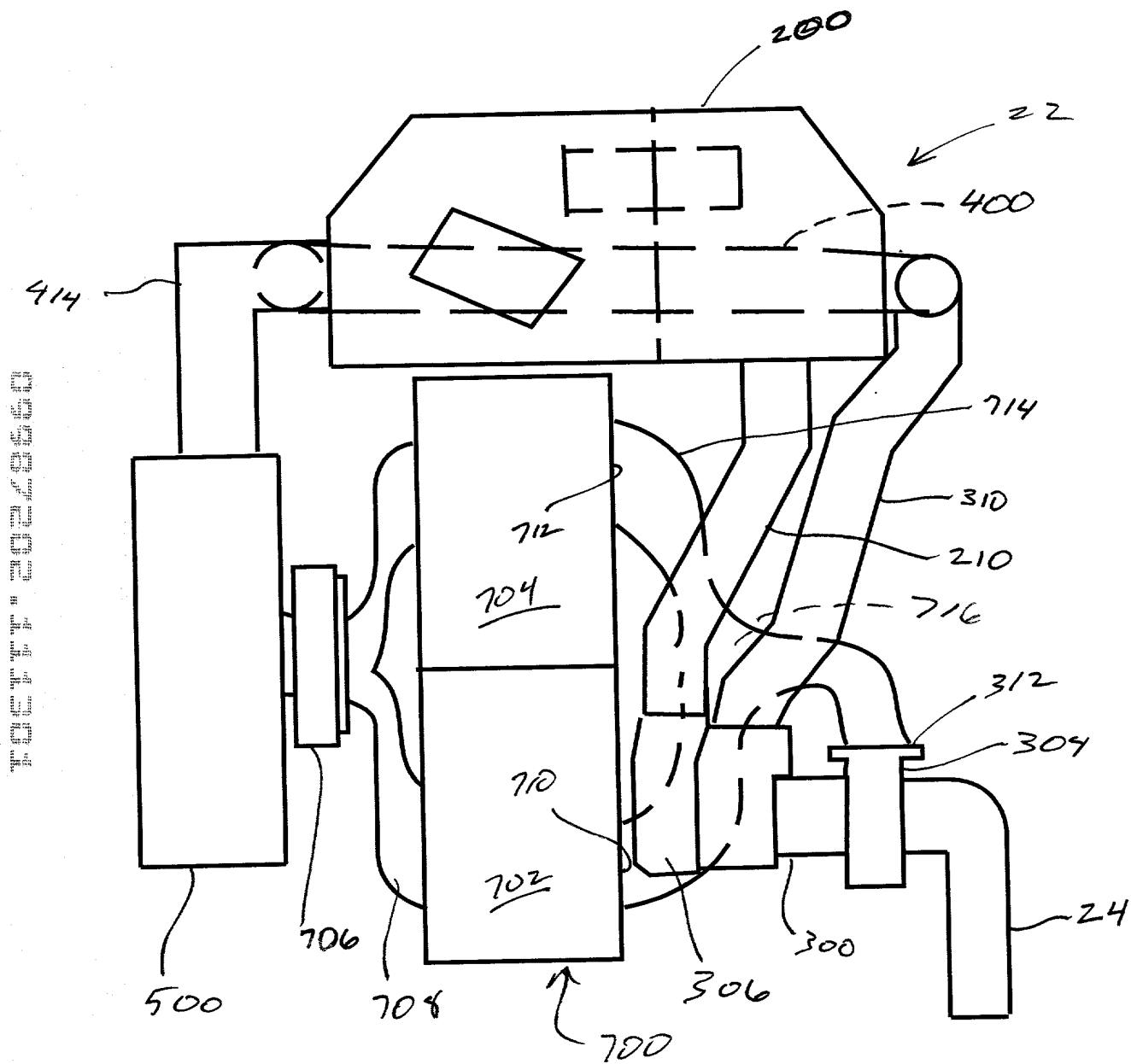


Figure 12

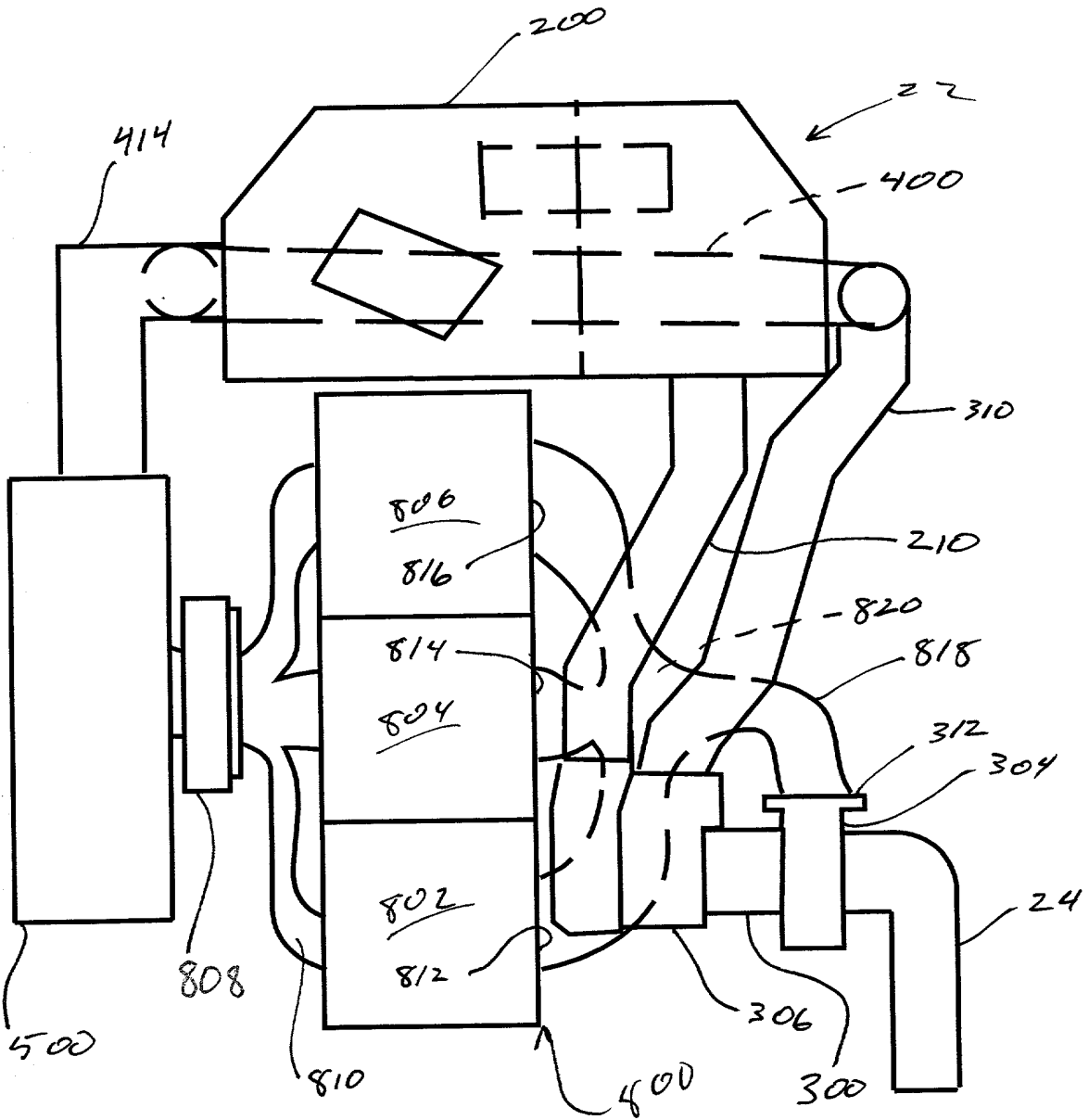


Figure 13

FIG. 14 is a schematic diagram of a system 100 for processing a material 102.

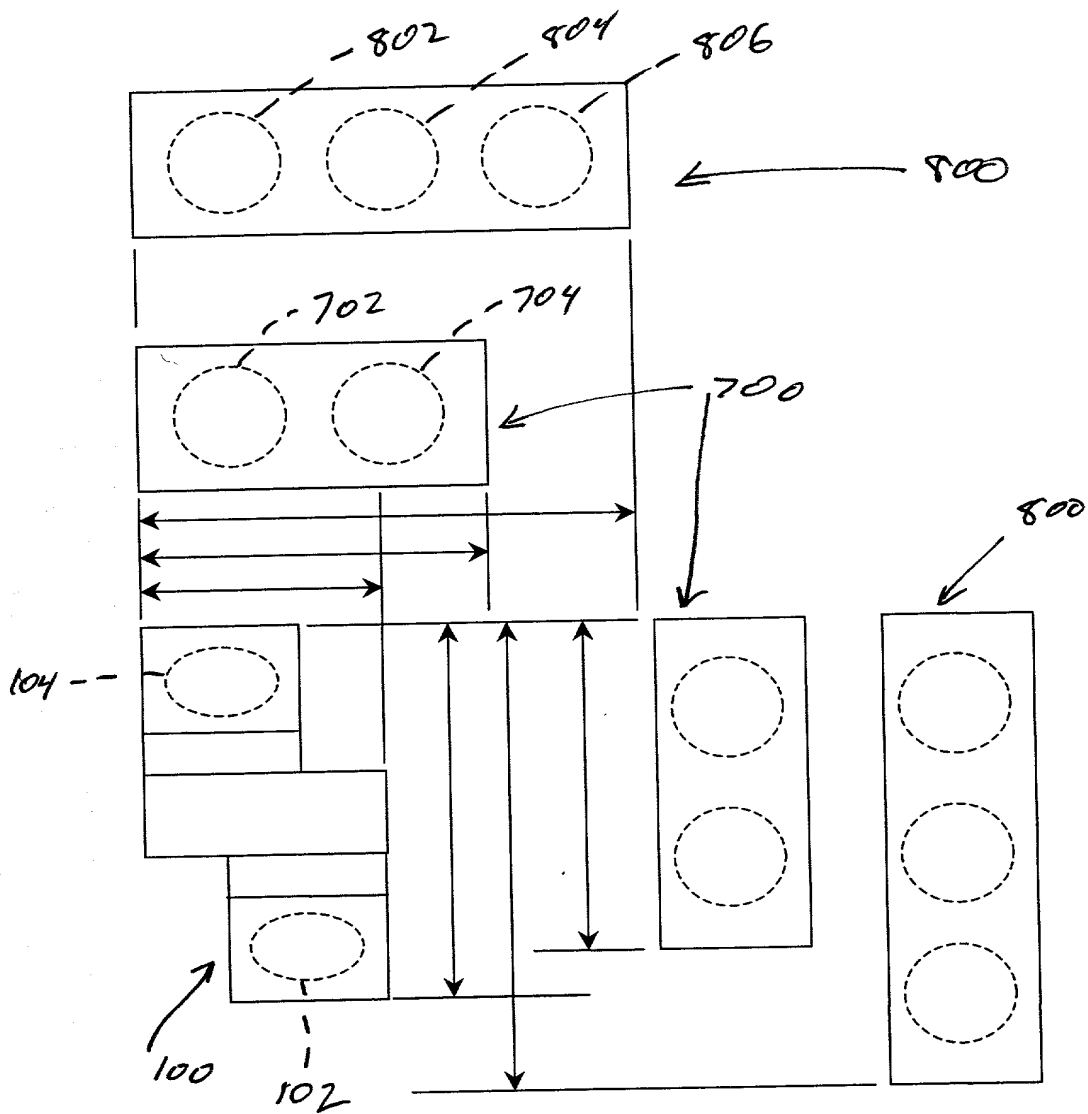


Figure 14

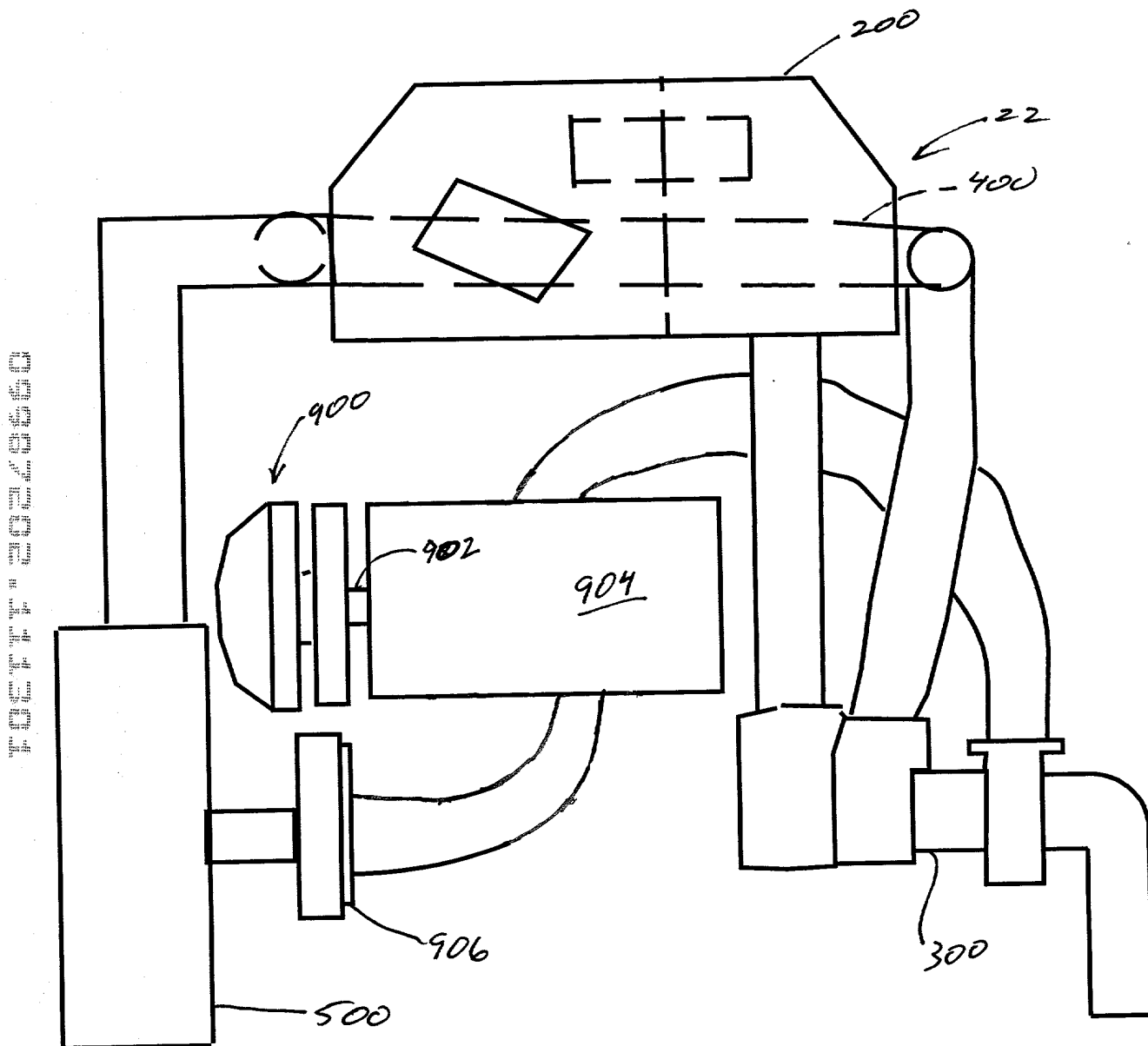


Figure 15

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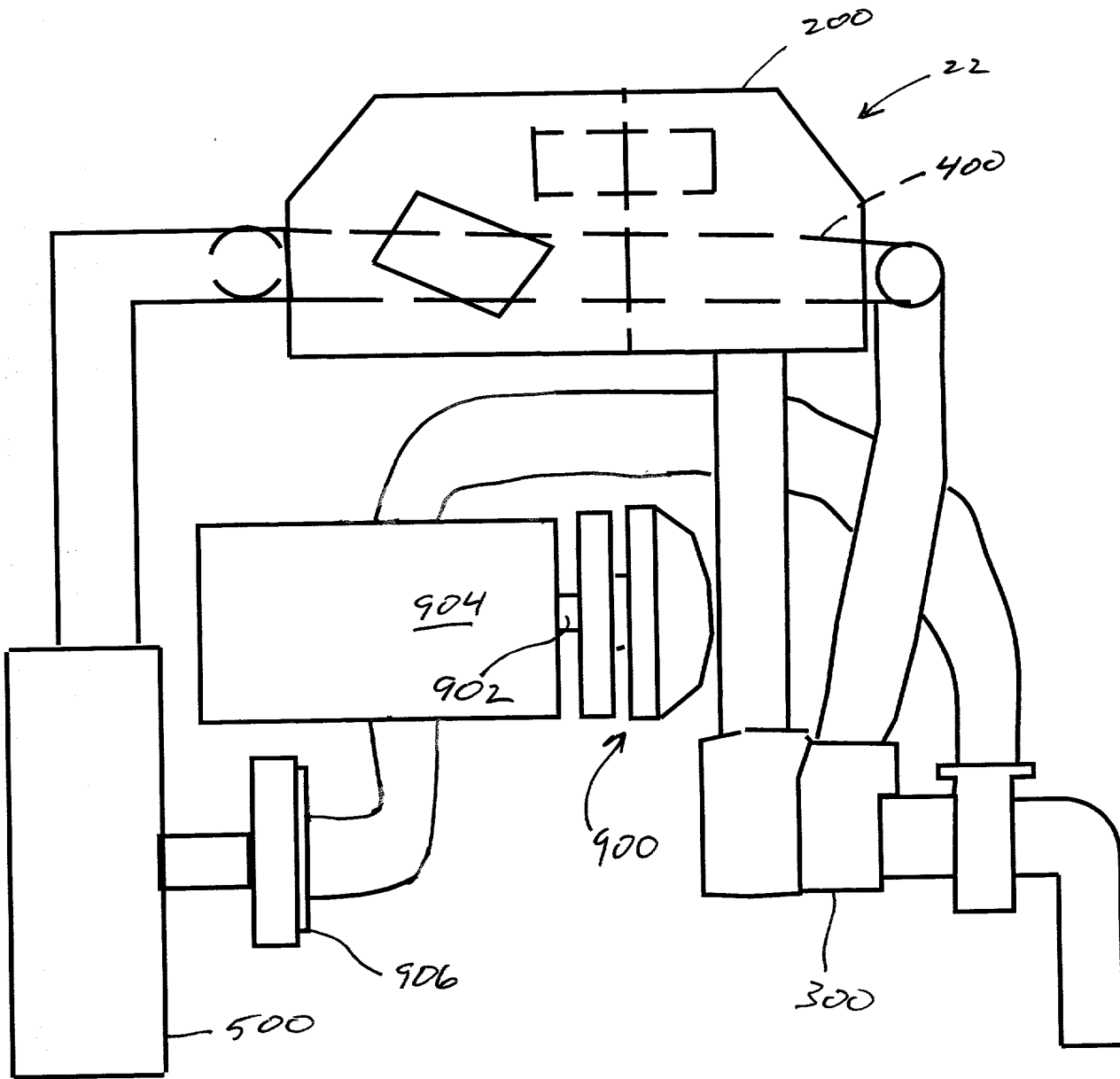


Figure 16